# CONSTRUCTION OF GREEN'S FUNCTION IN TERMS OF GREEN'S FUNCTION OF LOWER DIMENSION 

PMM Yol. 32, No. 3, 1968, pp. 414420
V.L. INDENBOM and S.S. ORLOV
(Moscow)
(Received August 14, 1967)

A method of constructing a Green's tensor for systems of linear differential equations with constant coefficients, defined in a space of odd dimensionality, in terms of the Green's tensor for a hyperplane, is given. Fundamental problems of the classical theory of elasticity of the internal stress theory and of the dislocation theory, are used as examples of the application of the derived method to the problems in the field theory in anisotropic media.

1. It is well known, that an $n$-dimensional scalar, or tensor Green's function $G(x)$ can be reduced, using the method of descent, to a Green's function $\Phi(x, T)$ for an arbitrary ( $n=$ 1)-dimensional sabspace $x_{i} \tau_{i}=0$, orthogonal to the vector $T$. In an unbounded space we have

$$
\begin{equation*}
\Phi(\mathbf{x}, \tau)=\int_{-\infty}^{\infty} G(\mathbf{x}-\tau s) \tau d s \tag{1.1}
\end{equation*}
$$

where $T$ is the length of the vector $T$. Since $\Phi(x, T)$ is a function of the first argument, therefore, it is not a function of the $n$-dimensional vector $X$, it is a function of the $(n-1)$ dimensional vector $\mathrm{X}-\boldsymbol{T}(\mathrm{x} \tau) \tau^{-2}$.

We shall show that, for a wide class of equations given in an infinite, odd-dimensional space, solution of the converse problem is possible.
2. Lemma. Suppose that a function is given in an $n$-dimensional space, satisfying the condition

$$
\begin{equation*}
G(\alpha x)=\alpha^{-l} \operatorname{sign} \alpha G(x) \tag{2.1}
\end{equation*}
$$

where $k$ is a natural number. Then $G(x)$ can be determined in terms of the function $\Phi(\mathbf{x}, \tau)$ defined by (1.1), with the help of the following expressions:

$$
\begin{array}{cc}
G(\tau)=-\frac{1}{2 \tau} x_{i} \frac{\partial}{\partial x_{i}} \Phi(\mathbf{x}, \tau) & (k=1) \\
G(\tau)=\frac{(-1)^{i-1}}{2(k-2)!} D^{i-1} \frac{\Phi(\mathbf{x}, \tau)}{\tau} \quad(k \geqslant 2) \quad D=x_{j} \partial(\ldots) / \partial \tau_{j} \tag{2.3}
\end{array}
$$

Proof. $2.1^{\circ}$. If $k=1$, the integral (1.1) diverges logarithmically and the definition of $\Phi(\mathbf{X}, T)$ must therefore be made more precise. Nevertheless, the gradient of this function can be determined uniquely

$$
\begin{equation*}
\frac{\partial}{\partial x_{i}} \Phi(\mathbf{x}, \tau)=\Phi_{, i}(\mathbf{x}, \tau)=\int_{-\infty}^{\infty} G_{, i}(\mathbf{x}-\tau s) \tau d s \tag{2.4}
\end{equation*}
$$

Let us multiply (2.4) by $x_{i}$. Using the Euler's theorem for homogeneous functions, we obm tain

$$
x_{i} \mathcal{D}_{, i}(\mathrm{x}, \tau)=-\int_{-\infty}^{\infty} G(\mathrm{x}-\tau s) \tau d s+\int_{-\infty}^{\infty} s \tau_{i} G_{, i}(\mathrm{x}-\tau v) \tau d s
$$

Observing that

$$
\tau_{i} G_{, i}(x-\tau v)=-\frac{d}{d s} G(x-\tau s)
$$

and integrating its right-hand side by parts, we obtain

$$
x_{i} \Phi_{, i}(\mathrm{x}, \tau)=-\left.s \tau G(\mathrm{x}-\tau \varepsilon)\right|_{s=-\infty} ^{\mathrm{s}=\infty}=-2 \tau G(\tau)
$$

$2.2^{\circ}$. When $k>2$, we apply the operator $D$ to both parts of the Eq.

$$
\begin{equation*}
\frac{\Phi(\mathbf{x}, \boldsymbol{\tau})}{\tau}=\int_{-\infty}^{\infty} G(\mathbf{x}-\boldsymbol{\tau} s) d s \tag{2.5}
\end{equation*}
$$

and use the Euler's theorem to obtain

$$
D \frac{\lceil\Phi(\mathbf{x}, \tau)}{\tau}=-\int_{-\infty}^{\infty} s x_{i} G_{, i}(\mathbf{x}-\tau s) d s=k \int_{-\infty}^{\infty} s G(\mathbf{x}-\tau s) d s-\int_{-\infty}^{\infty} s^{2} \tau_{i} G_{, i}(\mathbf{x}-\tau s) d s
$$

This on integration by parts, yields

$$
D \frac{\Phi(\mathbf{x}, \tau)}{\tau}=(k-2) \int_{-\infty}^{\infty} s G(\mathbf{x}-\tau s) d s+\left.s^{2} G(\mathbf{x}-\tau s)\right|_{s=-\infty} ^{s=-\infty}
$$

hence

$$
D \frac{\Phi(\mathbf{x}, \tau)}{\tau}=-2 G(\tau) \quad(k=2) ; \quad D \frac{\Phi(x, \tau)}{\tau}=\int_{-\infty}^{\infty}(k-2) s G(\mathbf{x}-\tau s) d s \quad(k>2)
$$

Applying the operator $D^{\mathbf{k}-2}$ to both parts of (2.5), we obtain

$$
D^{k-2} \frac{\Phi(\mathrm{x}, \tau)}{\tau}=(k-2)!\int_{-\infty}^{\infty} s^{k-2} G(\mathrm{x}-\tau s) d s
$$

Then

$$
D^{k-1} \frac{\Phi(\mathbf{x}, \tau)}{\tau}=\left.(k-2)!s^{k} G(\mathbf{x}-\tau s)\right|_{s=-\infty} ^{s=\infty}
$$

from which, taking into account (2.1), we obtain (2.4).
3. Let us obtain the conditions of applicability of the Lemma of Section 2 to the Green's tensors. To shorten the notation, we shall employ Greek letters for the indices assuming $n^{l}$ values, and use a single index to denote the components of tensors of rank $l$. (As before, Latin alphabet will be ased for the indices assuming $n$ values).

Let a linear, homogeneous, $m$-th order differential operator with constant coefficients

$$
L_{\alpha \beta}=A_{\alpha \beta p_{1} \ldots p_{m}} \nabla_{p_{1} \ldots} \nabla_{p_{m}}
$$

be given in an $n$-dimensional unbounded space.
We shall consider the equation

$$
\begin{equation*}
L_{\alpha \beta} \psi_{\beta}(\mathbf{x})+f_{\alpha}(\mathbf{x})=0 \tag{3.1}
\end{equation*}
$$

and prove the following theorem.
Theorem 1. A Green's tensor of the system (3.1) or its derivatives, can be constructed in odd-dimensional spaces in terms of a Green's tensor for hyperplanes, using relations of the type (2.2) and (2.3).

Proof. We shall assume that a Green's tensor $G_{\beta \gamma}(\mathbf{x})$ exists, satisfying the Eq.

$$
\begin{equation*}
L_{\alpha \beta} G_{\beta \gamma}(\mathrm{x})+\delta_{\alpha \gamma} \delta(\mathrm{x})=0 \tag{3.2}
\end{equation*}
$$

Taking into account the fact that

$$
G_{\beta \gamma}(\alpha x)=\alpha^{m-n}(\operatorname{sign} \alpha)^{m} G_{\beta \gamma}(\mathbf{x})
$$

and putting $n-m=k$, we have

$$
G_{\beta \gamma}(\alpha x)= \begin{cases}\alpha^{-k} G_{\beta \gamma}(x), & \text { if } n \text { is even }  \tag{3.3}\\ \alpha^{-k} \operatorname{sign} \alpha G_{\beta \gamma}(x) & \text { if } n \text { is odd }\end{cases}
$$

If $k<0$, then we consider the derivatives of the Green's tensor

$$
G_{3 Y, p_{1}, \ldots, p_{1-k}}(\alpha x)= \begin{cases}\alpha^{-1} G_{\beta Y, p_{1}, \ldots, p_{1-k}}(\mathbf{x}), & \text { if } n \text { is even } \\ \alpha^{-1} \operatorname{sing} \alpha G_{\beta \gamma, p_{1}, \ldots, p_{1-k}}(x), & \text { if } n \text { is odd }\end{cases}
$$

Solution of the problem for the hyperplane $x_{i} \tau_{i}=0$ can be obtained with help of the Green's tensor $\Phi_{\beta \gamma}(x, \tau)$ defined by the following system of equations

$$
\begin{equation*}
L_{\alpha \beta} \Phi_{\beta \gamma}(\mathbf{x}, \tau)+\delta_{\alpha \gamma} \int_{-\infty}^{\infty} \delta(\mathbf{x}-\tau s) \tau d s \tag{3.7}
\end{equation*}
$$

If $k>1$, we have

$$
\begin{equation*}
\Phi_{\beta \gamma}(\mathbf{x}, \tau)=\int_{-\infty}^{\infty} G_{\beta \gamma}(\mathbf{x}-\tau s) \tau d s \tag{3.8}
\end{equation*}
$$

If $k<0$, we can obtain the derivatives of the Green's tenso:

$$
\begin{equation*}
\Phi_{\alpha \beta, p_{1}, \ldots, p_{1-k i}}(\mathbf{x}, \tau)=\int_{-\infty}^{\infty} G_{\alpha \beta, p_{1}, \ldots, p_{1-k}}(\mathbf{x}-\tau \boldsymbol{\tau}) \tau d s \tag{3.9}
\end{equation*}
$$

Combining the relations (3.4), (3.6), (3.8) and (3.9) with the conditions of the Lemma, we confirm the validity of the theorem.
4. Let us now assume that the field $\psi$ cannot be constructed with the help of the point sources, i,e. that the system (3.1) does not admit the construction of the ordinary Green's tensor (3.2) and, that only a generalized Green's tensor $G_{a q 1 \ldots q_{r}}(\mathbf{x})$ exists, corresponding to an elementary extended source of $\psi$ (see e.g. [1]). We find, that for the subspace $x_{k} \tau_{k}=$ $=0$, the generalized Green's tensor $\Phi_{a}(x, \tau)$ has a projection on the $\tau$-direction and is, therefore, of lower rank than the tensor $G_{a q_{1} \ldots q_{r}}(x)$

$$
\begin{equation*}
\Phi(\mathbf{x}, \boldsymbol{\tau})=\tau_{q_{1}} \ldots \tau_{q_{r}} \tau^{1-r} \int_{-\infty}^{\infty} G_{q_{1} \cdots q_{r}}(\mathbf{x}-\tau s) d s \tag{4.1}
\end{equation*}
$$

(indices not involved in the contraction are omitted). We find that the Lema of Section 2 is not valid for (4.1), the following theorem can, however, be formulated.

Theorem 2. If the generalized Green's tensor $G_{\text {ad }} \ldots$... $q_{r}$ related to the generalized Green's tensors for the hyperplane $x_{i} \tau_{i}=0$ by (4.1) can be represented in the form

$$
\begin{equation*}
G_{\alpha q_{1} \ldots q_{r}}=e_{q_{1} p_{1}}^{t_{1}^{k_{1}}} \ldots e_{q_{r} p_{r}}^{t_{r}^{h} x_{p_{1}}} x_{p_{1}} \ldots x_{p_{r}} G_{\alpha t_{1} \ldots 1_{r} h_{1} \ldots h_{r}}^{\prime} \tag{4.2}
\end{equation*}
$$

where $e_{p q}^{j j}=\delta_{p}{ }^{i} \delta_{q}^{j}-\delta_{q}{ }^{i} \delta_{p}{ }^{\prime}$, and ' $^{\prime}$ satisfies (2.1), then

$$
\begin{equation*}
G_{a q_{1} \ldots q_{r}}(\tau)=\frac{1-1)^{h+r-1}}{2 r!(k-2)!} \frac{\partial^{r}}{\partial x_{q_{1}} \cdots \partial x_{q_{r}}} D^{k-1} \frac{\Phi_{\alpha}(\mathrm{x}, \tau)}{\tau^{1-r}} \tag{4.3}
\end{equation*}
$$

$\mathrm{Pr} \circ \circ \mathrm{f}$. Let as insert (4.3) into (4.2) and apply to both sides the operator $D^{k-1}$. Any function of the bivector

$$
y^{i j} \equiv e_{p q}^{i j} \tau_{p} x q
$$

will become zero under the action of this operator, therefore

$$
D^{k-1} \frac{\Phi_{\alpha}(\mathbf{x}, \tau)}{\tau^{1-r}}=y^{p_{1} q_{1}} \ldots y^{p_{r} q_{r}} D^{k-1} \int_{-\infty}^{\infty} G_{\alpha p_{1} \ldots p_{r} q_{1} \ldots q_{r}}^{\prime}(x-\tau s) d s
$$

Applying the results of the Lemma to the latter expression, we obtain

$$
\begin{equation*}
\frac{(-1)^{k-1}}{2(k-2)!} D^{k-1} \frac{\Phi_{\alpha}(\mathbf{x}, \tau)}{\tau^{1-r}}=y^{p_{1} q_{1}} \ldots y^{p_{r} q_{r} G_{\alpha p_{1} \ldots p_{r} q_{1} \ldots q_{r}}^{\prime}(\tau)} \tag{4.4}
\end{equation*}
$$

The $r$-fold contraction of the tensor ' $G$ ' with the bivector $y^{i j}$ in the right-hand side of (4.4), will be an $r$-th degree polynomial in the vector $X$, hence applying the operator $\partial^{r}(\ldots$.$) )$ $\partial x_{q_{1}} \ldots \partial x_{q_{t}}$ to both parts of (4.4), we obtain the required formula (4.3).
5. As an example, we shall consider some typical threedimensional problems of the theory of elasticity of anisotropic media, reducing them to investigation of plane problems, in which the complex variable methods can be utilized. Various types of sources appearing in the classical theory of elasticity (potential fields, ordinary Green's functions), in the dislocation theory (vortex fields, generalized Green's functions) and in the internal stress theory (potential and bivortical fields and corresponding ordinary and generalized Green's functions depending on the definition of the source) can furnish various examples of application of the above theorems. Classification of the sources, the terminology and the basic equations, are taken from [2 and 3].
5.1. Green'stensorforaconcentrated force. The Green's tensor $G_{i j}$ satisfying Eq.

$$
\begin{equation*}
C_{i j k i} G_{k m, l j}(\mathbf{x})+\delta_{i m} \delta(\mathbf{x})=0 \tag{5.1}
\end{equation*}
$$

defines the displacement field $u_{i}$ for a unit concentrated force, in an anisotropic medium with elastic moduli $C_{i j k l}$.

We know [4] that the solution of (5.1) can be obtained in the explicit form only for some isolated cases. In the two-dimensional case of the plane $x_{i} \tau_{i}=0$, the displacement field is described by the Green's tensor $\Phi_{i j}(x, T)$ satisfying the equation

$$
C_{i j k l} \Phi_{h m, l j}(\mathrm{x}, \tau)+\delta_{i m} \int_{-\infty}^{\infty} \delta(\mathrm{x}-\tau s) \tau d s
$$

By the Theorem I we have

$$
\begin{equation*}
G_{i j}(\tau)=-\frac{1}{2 \tau} x_{k} \frac{\partial}{\partial x_{k}} \Phi_{i j}(\mathbf{x}, \tau) \tag{5.2}
\end{equation*}
$$

$5.2^{\circ}$. Green'stensorforinternaldeformations. If the stresses are caused not by external forces but by internal deformations $\varepsilon_{i j}^{\circ}$ of arbitrary origin (e.g. thermoelastic, strictional, plastic e.a.), then the displacement field satisfies

$$
\begin{equation*}
C_{i j k l} u_{k, l j}=-C_{i j k \varepsilon_{k l, j}}^{\varepsilon^{o}} \tag{5.3}
\end{equation*}
$$

to which corresponds the following Green's tensor:

$$
\begin{equation*}
G_{i j k}=\sigma_{i j}^{k}=C_{i j l m} G_{l k, m} \tag{5.4}
\end{equation*}
$$

Here $\sigma_{i j}{ }^{k}$ denote the $i j$-component of the field of stress caused by a unit force acting $[2$, and 5] in the $k$-direction, while $G_{l k}$ is the 'Green's tensor for the concentrated force.
In the twodimensional case we have

$$
\begin{equation*}
\Phi_{i j k}=C_{i j l m} \Phi_{i k, m} \tag{5.5}
\end{equation*}
$$

By Theorem 1,

$$
\begin{equation*}
\delta_{i j}^{k}(\tau)=-\frac{1}{2} x_{l} \frac{\partial}{\partial \tau_{i}} \frac{\Phi_{i j k}(\mathrm{x}, \tau)}{\tau} \tag{5.6}
\end{equation*}
$$

i.e.

$$
\begin{equation*}
u_{k}(x)=-\frac{1}{2} \tau_{l} \frac{\partial}{\partial x_{l}} \int \Phi_{i j k}(\tau, X) \varepsilon_{i j}{ }^{\circ}\left(x^{\prime}\right) \frac{\left(d x^{\prime}\right)}{R} \quad\left(X=x-x^{\prime}, R=|X|\right) \tag{5.7}
\end{equation*}
$$

For elastic deformations
$\varepsilon_{i j}=\frac{1}{2}\left(u_{i, j}+u_{j, i}\right)-\varepsilon_{i j}{ }^{\circ}=\int\left\{\frac{1}{2}\left[\sigma_{m n, j}^{i}(\mathbf{X})+\sigma_{m n, i}^{j}(\mathbf{X})\right]-\delta_{i n} \delta_{j m} \delta(\mathbf{X})\right\} e_{m n}^{0}\left(\mathbf{x}^{\prime}\right)\left(d \mathbf{x}^{\prime}\right)$ taking into account the fact that the index of homogeneity of the functions $\sigma_{i j}^{k}, j(x)$ and $\delta(x)$ is equal to -3 we have according to Theorem 1 , the following relation:

$$
\begin{equation*}
\varepsilon_{i k}(\mathrm{x})=\frac{1}{2} \tau_{m} \tau_{n} \frac{\partial^{2}}{\partial x_{m} \partial x_{n}} \int E_{j l}^{i k}(\tau, \mathbf{X}) \varepsilon_{j l}^{0}\left(\mathbf{x}^{\prime}\right) \frac{\left(d \mathbf{x}^{\prime}\right)}{R} \tag{5.8}
\end{equation*}
$$

where $E_{i j}^{\prime k}(\mathbf{X}, T)$ is a two-dimenaional Green's tensor describing the field of elastic deformatione $\varepsilon_{i k}(X, T)=\varepsilon^{\circ}{ }_{1 l} E_{1 l}^{i k}(X, T)$ for an olementary source of a two-dimensional field

$$
\begin{equation*}
\varepsilon_{i j} j^{\circ}(\mathrm{x})=\mathrm{E}_{i j} \int_{-\infty}^{\infty} \delta(\mathrm{x}-\tau s) \tau d s \tag{5.9}
\end{equation*}
$$

5.30. Green's tensorforinternaldistortions. If the asymmetric internal distortion tensor $u_{i j}{ }^{\circ}$ is given, then the tensor $\sigma_{i f}{ }^{k}$ defining the displacement fields $u_{k}$ will again be the Green's tensor. Unlike the case $5.2^{\circ}$, we can constract not only an olastic deformation tensor (5.7), but also an asymmetric elastic diatortion tensor

$$
\begin{aligned}
& u_{i k}=u_{k, i}-u_{i .}^{\circ}=\int\left[\sigma_{m, i}^{k}(\mathbf{X}) u_{n m}^{\circ}\left(\mathbf{x}^{\prime}\right)-\delta(\mathbf{X}) u_{i k}^{0}\left(\mathbf{x}^{\prime}\right)\right]\left(d x^{\prime}\right)= \\
& =\int\left[\sigma_{m n, i}^{k}(\mathbf{X}) u_{n m}^{\circ}\left(\mathbf{x}^{\prime}\right)+X_{j, i} \delta_{i}(\mathbf{X}) u_{j i}^{\circ}\left(\mathbf{x}^{\prime}\right)\right]\left(d \mathbf{x}^{\prime}\right)= \\
& =\int\left[\sigma_{m n, i}^{k}(\mathbf{X}) u_{n m}^{\bullet \cdot}\left(\mathbf{x}^{\prime}\right)+X_{j} \sigma_{m n, i n}^{k}(\mathbf{X}) u_{j m}^{o}\left(\mathbf{x}^{\prime}\right)\right]\left(d \mathbf{x}^{\prime}\right)=\int\left[\sigma_{m n, i}^{k}(\mathbf{X}) X_{j} u_{j m, n}^{o}\left(\mathbf{x}^{\prime}\right)\right]\left(d \mathbf{x}^{\prime}\right) \\
& \text { 5.4ㅇ. Green's tensorfordislocations. Wearegivena } \\
& \text { vortex aource and the dinlocation density tensor }
\end{aligned}
$$

$$
\begin{equation*}
\alpha_{i j}=-e_{i k i} u_{l j, k}=e_{i k l} u_{l j, k}^{\circ} \tag{5.10}
\end{equation*}
$$

Using the fact that

$$
\int\left[X_{j} \sigma_{m n, i}^{k}(\mathbf{X}) u_{n m, j}^{\circ}\left(\mathbf{x}^{\prime}\right)\right]\left(d \mathbf{x}^{\prime}\right)=0
$$

which can easily be confirmed porforming the integration by parts and assuming that the homogenelty index of $\sigma_{\mathrm{mn}, \mathrm{i}}^{\mathrm{k}}$ is equal to - 3, we can transform (5.9) into

$$
\begin{equation*}
u_{i k}=\int x_{j} \sigma_{m n, i}^{k}\left[u_{j m, n}^{0}\left(x^{\prime}\right)-u_{n m, j}^{o}\left(x^{\prime}\right)\right]\left(d x^{\prime}\right)=\int \sigma_{m n, i}^{k}(\mathbf{X}) e_{n j l} X_{j} \alpha_{l m}\left(x^{\prime}\right)\left(d x^{\prime}\right) \tag{5.11}
\end{equation*}
$$

which correaponds to (4.2). The elementary, two-dimensional field source (rectilinear dislocation) is then given by

$$
\begin{equation*}
\alpha_{i j}(\mathrm{x})=\tau_{i} b_{j} \int_{-\infty}^{\infty} \delta(\mathrm{x}-\tau s) d s \tag{5.12}
\end{equation*}
$$

which corresponds to (4.1). In the case of elnatic distortion resulting from the rectilinear dislocation where the Burgers vector $b$ is given by

$$
u_{i k}(\mathbf{x}, \tau, \mathrm{~b})=b_{m} u_{i k}^{m}(\mathbf{x}, \tau)
$$

we find, from (5.11),

$$
\begin{equation*}
u_{i . .}^{m}(x, v)=e_{n j l^{x}} \tau_{l} \int_{-\infty}^{\infty} \sigma_{m n, i}^{k}(\mathrm{x}-\tau s) d s \tag{5.13}
\end{equation*}
$$

from which, uaing the Theorem 2, we obtain the following expression for the generalized Green's tensor:

$$
e_{n j 1} \tau_{j} \sigma_{m n, i}^{k}(\tau)=-\frac{1}{2} \frac{\partial}{\partial x_{l}}\left[x_{j} x_{n} \frac{\partial^{2}}{\partial \tau_{j} \partial \tau_{n}} u_{i k}^{m}(x, \tau)\right]
$$

and

$$
\begin{equation*}
u_{i k}(x)=-\frac{1}{2} \frac{\partial^{2}}{\partial x_{l} \partial x_{j}}\left[\delta_{l q} \tau_{j}+\delta_{j q} \tau_{l}+\tau_{l} \tau_{j} \frac{\partial}{\partial \tau_{q}}\right] \int u_{i k}^{m}(\tau, X) \alpha_{q m}\left(x^{\prime}\right)\left(d x^{\prime}\right) \tag{5.14}
\end{equation*}
$$

for the distortion field resulting from the given distribation of dislocations, in terms of the distortion field (5.13) cansed by rectilinear dislocations.
5.5 ${ }^{\circ}$. Green'stensorforthedeformationincompatibility, Let a deformation incompatibility tensor be given in the form of a vortex mource

$$
\begin{equation*}
\eta_{i j}=-e_{i k m} e_{j l m} \varepsilon_{m n, k l}=e_{i k m} e_{j l n} \varepsilon_{m n, h l}^{0} \tag{5.15}
\end{equation*}
$$

Using Expression (5.7) for the field of elastic deformation generated by the given internal deformation distribution and following the procedure used in deriving the generalized 'Green's tensor for the dislocations, we obtain

$$
\begin{equation*}
\varepsilon_{i j, h}(\mathrm{x})=\frac{1}{4} e_{m p s} e_{n q t} \int X_{p} X_{q}\left[\sigma_{m n, j k}^{i}(\mathrm{X})+\sigma_{m n, i k}^{j}(\mathrm{X})\right] \eta_{s t}\left(\mathrm{x}^{\prime}\right)\left(d \mathrm{x}^{\prime}\right) \tag{5.16}
\end{equation*}
$$

The expression

$$
\begin{equation*}
\eta_{i j}=\tau_{i} \tau_{j} \tau^{-1} \int_{-\infty}^{\infty} \delta(\mathrm{x}-\tau s) d s \tag{5.17}
\end{equation*}
$$

defines the elementary, two-dimensional field source.
By Theorem 2, we have

$$
\begin{equation*}
e_{i j, h}(x)=-\frac{1}{8} \frac{\partial^{2}}{\partial \tau_{s} \partial \tau_{t}} \tau_{m} \tau_{n} \tau_{l} \frac{\partial^{s}}{\partial x_{m} \partial x_{n} \partial x_{l}} \int R e_{i j, h}(\tau, X) \eta_{s i}\left(x^{\prime}\right)\left(d x^{\prime}\right) \tag{5.18}
\end{equation*}
$$

Differentiating (5.16) and (5.18) with respect to $x_{k}$ we obtain the Laplacian of the elastic deformations, and this, in turn, can be used to constrnct ' $\varepsilon_{i j}$ ' with the aid of the given Green's function of the Poisson equation.
6. The method of constructing'Green's tensors discussed in Section 5 can be made more efficient and uniform if, instead of the classical 'Greon's tensor $G_{i j}(X)$ of the theory of elasticity, we use as a starting point the tensor

$$
\begin{equation*}
G_{i j h . L}(\mathrm{x})=-\frac{1}{8 \pi} G_{\mathrm{i} j m n} \int R_{, p p l m} G_{\mathrm{ln}}\left(\mathrm{x}^{\prime}\right)\left(d \mathrm{x}^{\prime}\right) \tag{6.1}
\end{equation*}
$$

which can be constructed [3] as easily, as $G_{j j}$. Since $G_{i j h l}(\alpha, x)=|\alpha|^{-1} G_{i j h l} x$ we have, by Theorem 1,

$$
\begin{equation*}
G_{i j h l}(\tau)=-\frac{1}{2 \tau} x_{m} \frac{\partial}{\partial x_{m}} \Phi_{i j h l}(x, \tau) \tag{6.2}
\end{equation*}
$$

where $\Phi_{i j k l}(x, T)$ is a two-dimensional analog of the tensor $G_{i j k l}(\mathbf{X})$. From ( 6.1 ) the following formula follows:

$$
\begin{equation*}
C_{i j m n} G_{l n, m}=G_{i j h l, l} \tag{6.3}
\end{equation*}
$$

enabling na to express'Green's tensors given in $5.2^{\circ}$ to $5.4^{\circ}$ in terms of the tensor $G_{i j k l}$

$$
\begin{gather*}
u_{k}(\mathrm{x})=-\int G_{i j h l, l}(\mathrm{X}) \varepsilon_{i j}{ }^{\circ}\left(\mathrm{x}^{\prime}\right)\left(d \mathrm{x}^{\prime}\right)  \tag{6.4}\\
\mathrm{e}_{i j}(\dot{\mathrm{x}})=-\frac{1}{2} \int\left[G_{m n i j, h k}+G_{m n j i, k l}\right] \varepsilon_{m n}^{\circ}\left(\mathrm{x}^{\prime}\right)\left(d \mathrm{x}^{\prime}\right)-\varepsilon_{i j}^{\circ}  \tag{6.5}\\
u_{i k}(\mathrm{x})=-\int G_{m n l, i_{i} p p} e_{n j!} X_{j} \alpha_{l m}\left(\mathrm{x}^{\prime}\right)\left(d \mathrm{x}^{\prime}\right) \tag{6.6}
\end{gather*}
$$

and obtain an explicit form of the Green's tensors for the elastic deformation discussed in $5.5^{\circ}$

$$
\begin{equation*}
\varepsilon_{i j}(x)=-\frac{1}{2} e_{m i p} \int\left[e_{n j q} G_{m n i k}+e_{n i q} G_{m n j l}\right] \eta_{p q}\left(x^{\prime}\right)\left(d x^{\prime}\right) \tag{6.7}
\end{equation*}
$$

as well as the following internal stresses

$$
\begin{equation*}
\sigma_{i j}(x)=-C_{i j h i} e_{m t p} e_{n e q} \int G_{m n l i t} \eta_{p q}\left(\mathbf{x}^{\prime}\right)\left(d \mathbf{x}^{\prime}\right) \tag{6.8}
\end{equation*}
$$

In particular we note that, using the tensor $G_{i j k l}$ we can construct a dislocation field of a unit dislocation loop (an analog of the Burges formula for the anisotropic medium)

$$
\begin{equation*}
u_{i}=\frac{b_{i}}{4 \pi} \Omega+e_{l j m} b_{k} \oint_{C} G_{h l i j}(\mathbf{X}) d x_{m} \tag{6.9}
\end{equation*}
$$

7. The above results admit a simple geometric interpretation. Since action of the sources in different directions in the anisotropic medium could not be compared with each other we have made use of the similarity rule (2.1) for the sources acting along the same direction replacing the existing distribution of sources, with another distribution exerting the same action on the point under consideration. Then we can base the construction of the $n$-dimensional Green's function $G(x)$ in terms of an ( $n-1$ )-dimensional Green's function $\Phi(x, \tau)$, on the process of replacement of a line source of constant strength corresponding to the function $\Phi(x, T)$, by another line source situated not along the $T$-axis, but along the $X$-axis, and of varying strength distributed along the source according to the law: $s^{k-2}$ sign $s$.

Indeed

$$
\begin{equation*}
=\int_{-\infty}^{\infty} s^{i} \operatorname{sign} s G\left(\frac{x}{s}-\tau\right) \tau d s=-\int_{-\infty}^{\infty}\left(-s^{\prime}\right)^{i-2} \operatorname{sign} s^{\prime} G\left(\tau-\mathbf{x} s^{\prime}\right) \tau d s^{\prime} \tag{7.1}
\end{equation*}
$$

where $s^{\prime}=s^{-1}$, and we find that the $(k-1)$-th derivative of the field in the direction of the source, corresponds to the point source field, i.e. yields a Green's function.

The similarity rule can be used in the same manner to express elastic distortions in terms of the first moment of the dislocation distribution, and the gradient of elastic deforman tions in terms of the second moment of the deformation incompatibility distribution. Geometric approach to the analysis of various source fields based on the similarity relations was developed by the authors in [6], while [7] deals with the application of the method to the theory of dislocations.

## BIBLIOGRAPHY

1. Kunin, I.A., Internal stresses in an anisotropic elastic medium. PMM, Vol. 128, No. 4, 1964.
2. Indenbom, V.L., Internal Stress in Crystals. Theory of crystal defects. Academia. Prague, 1966.
3. Indenbom, V.L.; Types of Defects in a Lattice. Theory of Dislocations. Physics of Crystals with Defects., Tbilisi, Vol. 1, 1966.
4. Lifshits, I.M. and Rozentsveig, L.N., Construction of the Green's tensor for the basic equation of the theory of elasticity for the case of an infinite, elastic-anisotropic medium. ZhETF, Vol. 17, No. 9, 1947.
5. Maizel', V.M., Temperature Problems of the Theory of Elasticity. Kiev, Izd. Akad. Nauk USSR, 1951.
6. Indenbom, V.L. and Orlov, S.S., Solution of the threedimensional anisotropic problems of the theory of elasticity using line sources. Kristallografiia, Vol. 12, No. 6, 1967.
7. Indenbom, V.L. and Orlov, S.S.* Dislocation in anisotropic media. ZhETF, 15 th October, 1967.
